

# Tutorial 2: Unconstrained optimization

## GIAN Short Course on Optimization: Applications, Algorithms, and Computation

Sven Leyffer

Argonne National Laboratory

September 12-24, 2016

# Theory of Optimality Conditions

1. Prove Theorem 3.1.1 (necessary conditions for a local min).  
*Hint:* Consider  $f(x)$  along lines  $s$  and use the 1D conditions.
1. Consider  $f(x) = 2x_1^3 - 3x_1^2 - 6x_1x_2(x_1 - x_2 - 1)$ . Plot  $f(x)$  in domain  $[-1, 1]^2$  using Matlab. Find its gradient and Hessian matrix, and find and classify all its stationary points.
1. Consider  $f(x) = x^2$  with global minimum at  $x = 0$ . Show that iterates,  $x^{(k+1)} = x^{(k)} + \alpha_k s^{(k)}$ , defined  $s^{(k)} = (-1)^{k+1}$  and  $\alpha_k = 2 + 3/2^{k+1}$  starting from  $x^{(0)} = 2$  satisfy  $s^T g < 0$  and  $f^{(k+1)} < f^{(k)}$ . Plot iterates using Matlab, and show that Algorithm 6.1 does not converge to a stationary point.



## Tutorial 2: Armijo Line Search

- Write a Matlab function that implements the Armijo line-search. Your function should be callable from other matlab routines, e.g.

```
% ArmijoLineSearch.m Implementation of Armijo line search
function [alpha, j, info]
    = ArmijoLineSearch( x, dx, g, ObjFun, varargin )
```

```
% ... define the constants of the search
t      = 1.0;          % ... initial step size
beta   = 0.5 ;        % ... back-tracking factor
maxf   = 10;          % ... maximum number of function evals
sigma  = 0.1;         % ... sufficient reduction parameter
```

- Use the Matlab function `evalf` and function pointers to pass different `ObjFun` arguments.



## Tutorial 2: Steepest Descend

- Test the line-search using the Powell function (`powell.m`), and the Rosenbrock function (`rosenbrock.m`), available on the web-site. In each case display the actual and predicted reduction for your step.
- Implement the steepest descend method with an Armijo line search in Matlab.
  - You can either implement your own line-search (preferred), or use mine.
  - Test the method on the two example above, and the chained Rosenbrock function.
  - Use Matlab's `contour` function to plot the contours (in 2D), and the progress of your method.
  - Starting points are  $x = (-1.5; 0.5)$  for Rosenbrock, and  $x = (1; 1)$  for Powell, and  $x = (-1; -1; \dots; -1)$  for chained Rosen.



## Tutorial 2: Newton & Quasi-Newton Methods

- Implement Newton's method with the Hessian modification.
  - Use your (or mine) steepest descend code as a starting point.
  - Use Matlab's eigenvalue functions, `eig`, to compute the eigenvalue.
  - Use Matlab's backslash operator to solve the Newton system.
  - Test the code again on our examples.
- Implement a quasi-Newton (or limited memory BFGS) method.



# Theory of Newton's Method

- 1 Show that Newton's method oscillates for  $\min f(x) = x^2 - x^4/4$ .
- 1 Prove quadratic convergence of Newton's method (Theorem 4.1.1)
- 1 Show that (??) holds for a quadratic function.
- 1 Show that the rank-one formula terminates for a quadratic:
  - Show by induction that  $H^{(k+1)}\gamma^{(j)} = \delta^{(j)}$  for all  $j = 1, \dots, k$ .
  - Hence conclude that the method terminates after  $n + 1$  iterations.
- 1 Program the limited-memory BFGS method in Matlab.
- 1 Apply Newton's method to nonlinear least-squares:

$$\underset{x}{\text{minimize}} \quad f(x) = \sum_{i=1}^m r_i(x)^2 = r(x)^T r(x) = \|r(x)\|_2^2.$$

What happens, if  $r_i(x)$  are linear? Can you propose a strategy for handling the case, where  $\nabla^2 r_i(x)$  are bounded, and  $r_i(x) \rightarrow 0$ ?

