

Mixed-Integer Nonlinear Optimization: Cutting Planes

GIAN Short Course on Optimization:
Applications, Algorithms, and Computation

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Outline

- 1 Branch-and-Cut for MINLP
- 2 Cutting Planes for MINLP
 - Perspective Cuts
 - Disjunctive Cuts



Mixed-Integer Nonlinear Optimization

Mixed-Integer Nonlinear Program (MINLP)

$$\begin{aligned} & \underset{x}{\text{minimize}} && f(x) \\ & \text{subject to} && c(x) \leq 0 \\ & && x \in X \\ & && x_i \in \mathbb{Z} \text{ for all } i \in I \end{aligned}$$

Assumptions:

- A1 X is a bounded polyhedral set.
- A2 f and c are twice continuously differentiable convex functions.
- A3 MINLP satisfies a constraint qualification.

Look at another class of branch-and-cut methods ...



Overview of Branch-and-Cut Methods

Extend nonlinear branch-and-bound

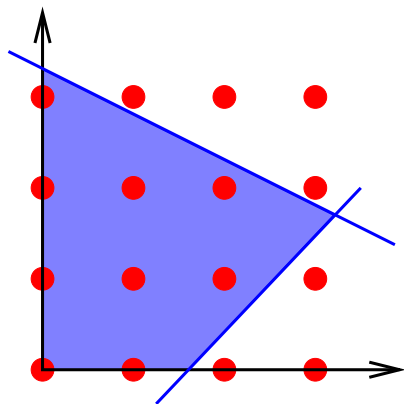
- ① Solve $NLP(l, u)$ at each node of tree
 - Generate a cut to eliminate fractional solution & re-solve
 - Only branch if solution fractional after some rounds of cuts
- ② Generation of good cuts is key [[Stubbs and Mehrotra, 1999](#)]
- ③ Hope that tree is smaller than BnB
- ④ Goal: get formulation closer to convex hull



Motivation for Branch-and-Cut Methods

Consider Polyhedron over Integer Lattice

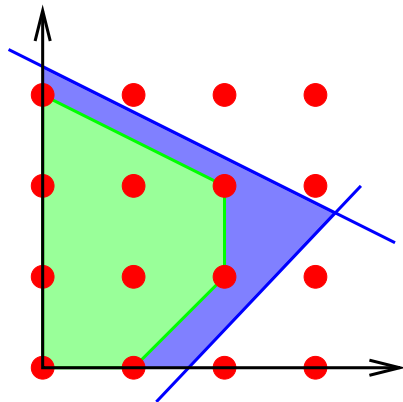
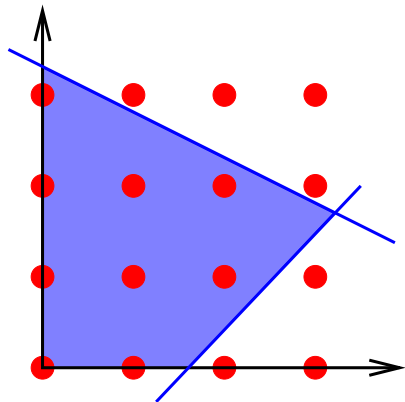
\Rightarrow minimizing $c^T x$ over set, gives (fractional) vertex



Motivation for Branch-and-Cut Methods

Consider Polyhedron over Integer Lattice

\Rightarrow minimizing $c^T x$ over set, gives (fractional) vertex



Consider Convex Hull of Feasible Integers

\Rightarrow minimizing $c^T x$ over set, gives **integer** vertex

Recall Nonlinear Branch-and-Bound

Solve NLP relaxation

$$\underset{x}{\text{minimize}} \ f(x) \quad \text{subject to} \ c(x) \leq 0, \ x \in X$$

- If $x_i \in \mathbb{Z} \ \forall i \in I$, then solved MINLP
- If relaxation is infeasible, then MINLP infeasible

... otherwise search tree whose nodes are NLPs:

$$\left\{ \begin{array}{l} \underset{x}{\text{minimize}} \ f(x), \\ \text{subject to} \ c(x) \leq 0, \\ \quad \quad \quad x \in X, \\ \quad \quad \quad l_i \leq x_i \leq u_i, \ \forall i \in I. \end{array} \right. \quad (\text{NLP}(I, u))$$

NLP relaxation is $\text{NLP}(-\infty, \infty)$



Branch-and-Bound for MINLP

Branch-and-bound for MINLP

Choose $\text{tol } \epsilon > 0$, set $U = \infty$, add $(\text{NLP}(-\infty, \infty))$ to heap \mathcal{H} .

while $\mathcal{H} \neq \emptyset$ **do**

 Remove $(\text{NLP}(l, u))$ from heap: $\mathcal{H} = \mathcal{H} - \{ \text{NLP}(l, u) \}$.

 Solve $(\text{NLP}(l, u)) \Rightarrow$ solution $x^{(l,u)}$

if $(\text{NLP}(l, u))$ is infeasible **then**

 | Prune node: infeasible

else if $f(x^{(l,u)}) > U$ **then**

 | Prune node; dominated by bound U

else if $x_i^{(l,u)}$ integral **then**

 | Update solution: $U = f(x^{(l,u)})$, $x^* = x^{(l,u)}$.

else

 | BranchOnVariable($x_i^{(l,u)}$, l , u , \mathcal{H})

end

end



Generic Nonlinear Branch-and-Cut

Choose a tol $\epsilon > 0$, set $U = \infty$, add $(\text{NLP}(-\infty, \infty))$ to heap \mathcal{H} .

while $\mathcal{H} \neq \emptyset$ **do**

Remove $(\text{NLP}(l, u))$ from heap: $\mathcal{H} = \mathcal{H} - \{ \text{NLP}(l, u) \}$.

repeat

Solve $(\text{NLP}(l, u)) \Rightarrow$ solution $x^{(l,u)}$.

if $(\text{NLP}(l, u))$ is infeasible **then**

| Prune node: infeasible

else if $f(x^{(l,u)}) > U$ **then**

| Prune node; dominated by bound U

else if $x_j^{(l,u)}$ integral **then**

| Update incumbent: $U = f(x^{(l,u)})$, $x^* = x^{(l,u)}$ & prune.

else **GenerateCuts** $(x^{(l,u)}, j)$... details later ;

until *no new cuts generated or node pruned*;

if $(\text{NLP}(l, u))$ not pruned & not incumbent **then**

| **BranchOnVariable** $(x_j^{(l,u)}, l, u, \mathcal{H})$

end

end



Cut Generation Overview

Subroutine: GenerateCuts ($x^{(l,u)}, j$)

// Generate a valid inequality that cuts off $x_j^{(l,u)} \notin \{0, 1\}$

Solve separation (NLP) problem in $x^{(l,u)}$ for valid cut.

Add valid inequality to (NLP(l, u)).

GenerateCuts: valid inequality to eliminate fractional solution

- Given fractional solution $x^{(l,u)}$ with $x_j^{(l,u)} \notin \{0, 1\}$.
- Let $\mathcal{F}(l, u)$ mixed-integer feasible set of node NLP(l, u).
- Find cut $\pi^T x \leq \pi_0$ such that
 - $\pi^T x \leq \pi_0$ for all $x \in \mathcal{F}(l, u)$
 - $\pi^T x^{(l,u)} > \pi_0$, i.e. $x^{(l,u)}$ violates the cut
- Solve a separation problem (e.g. an NLP) for cut $\pi^T x \leq \pi_0$

... lifting cuts makes them valid throughout the tree.



Example: Mixed-Integer Rounding (MIR) for MILP

Goal: Strengthen MILP relaxations of LP/NLP-based BnB
... iteratively add cuts to remove fractional LP solutions

Start by considering MIR cuts for “easy set”

$$S := \{(x_1, x_2) \in \mathbb{R} \times \mathbb{Z} \mid x_2 \leq b + x_1, x_1 \geq 0\},$$

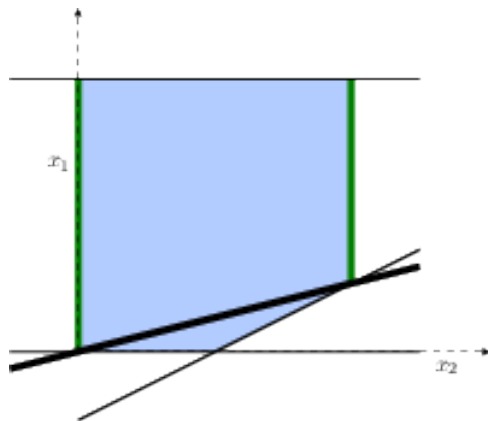
Let $f_0 = b - \lfloor b \rfloor$, then cut can show that

$$x_2 \leq \lfloor b \rfloor + \frac{x_1}{1 - f_0}$$

is valid for S



Example of Simple “MIR” Cut



MIR cut: $x_2 \leq 2x_1$ derived from $x_2 \leq \frac{1}{2} + x_1$.

Closer to convex hull \Rightarrow integral solutions to relaxation

Branch-and-Cut Challenges

Computational Considerations of Branch-and-Cut

- Cut-generation problem may be hard to solve
- Adds burden of additional NLP solves to BnB
 - Can solve LP instead of NLP, e.g. from OA
- Must add cut-management to solver
- Lifting cuts may help to make them valid in whole tree
- NLPs still don't hot-start

[[Stubbs and Mehrotra, 1999](#)] generate cuts only at root node



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 - Perspective Cuts
 - Disjunctive Cuts



Perspective Formulations

MINLPs use binary indicator variables, x_b , to model nonpositivity of $x_c \in \mathbb{R}$

Model as **variable upper bound**

$$0 \leq x_c \leq u_c x_b, \quad x_b \in \{0, 1\}$$

\Rightarrow if $x_c > 0$, then $x_b = 1$

Perspective reformulation applies, if x_b also in convex $c(x) \leq 0$

- Significantly improve reformulation
- Pioneered by [Frangioni and Gentile, 2006];
... strengthen relaxation using **perspective cuts**



Example of Perspective Formulation

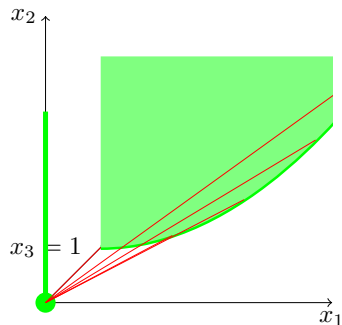
Consider MINLP set with three variables:

$$S = \left\{ (x_1, x_2, x_3) \in \mathbb{R}^2 \times \{0, 1\} : x_2 \geq x_1^2, \quad ux_3 \geq x_1 \geq 0 \right\}.$$

Can show that $S = S^0 \cup S^1$, where

$$S^0 = \left\{ (0, x_2, 0) \in \mathbb{R}^3 : x_2 \geq 0 \right\},$$

$$S^1 = \left\{ (x_1, x_2, 1) \in \mathbb{R}^3 : x_2 \geq x_1^2, \quad u \geq x_1 \geq 0 \right\}.$$



Example of Perspective Formulation

Geometry of convex hull of S :

Lines connecting origin ($x_3 = 0$) to parabola $x_2 = x_1^2$ at $x_3 = 1$

Define convex hull of S as $\text{conv}(S)$

$$:= \{(x_1, x_2, x_3) \in \mathbb{R}^3 : x_2 x_3 \geq x_1^2, x_3 \geq x_1 \geq 0, 1 \geq x_3 \geq 0, x_2 \geq 0\}$$

where $x_2 x_3 \geq x_1^2$ is defined in terms of **perspective function**

$$\mathcal{P}_f(x, z) := \begin{cases} 0 & \text{if } z = 0, \\ zf(x/z) & \text{if } z > 0. \end{cases}$$

Epigraph of $\mathcal{P}_f(x, z)$: cone pointed at origin with lower shape $f(x)$

$x_b \in \{0, 1\}$ indicator forces $x_c = 0$, or $c(x_c) \leq 0$ if $x_b = 1$ write

$$x_b c(x_c/x_b) \quad \dots \text{is tighter convex formulation}$$



Generalization of Perspective Cuts

[Günlük and Linderoth, 2012] consider more general problem

$$(P) \quad \min_{(x,z,\eta) \in \mathbb{R}^n \times \{0,1\} \times \mathbb{R}} \left\{ \eta \mid \eta \geq f(x) + cz, Ax \leq bz \right\}.$$

where

- 1 $X = \{x \mid Ax \leq b\}$ is bounded
- 2 $f(x)$ is convex and finite on X , and $f(0) = 0$

Theorem (Perspective Cut)

For any $\bar{x} \in X$ and subgradient $s \in \partial f(\bar{x})$, the inequality

$$\eta \geq f(\bar{x}) + c + s^T(x - \bar{x}) + (c + f(\bar{x}) - s^T \bar{x})(z - 1)$$

is valid cut for (P)



Stronger Relaxations [Günlük and Linderoth, 2012]

- z_R : Value of NLP relaxation
- z_{GLW} : Value of NLP relaxation after GLW cuts
- z_P : Value of perspective relaxation
- z^* : Optimal solution value

Separable Quadratic Facility Location Problems

$ M $	$ N $	z_R	z_{GLW}	z_P	z^*
10	30	140.6	326.4	346.5	348.7
15	50	141.3	312.2	380.0	384.1
20	65	122.5	248.7	288.9	289.3
25	80	121.3	260.1	314.8	315.8
30	100	128.0	327.0	391.7	393.2

⇒ Tighter relaxation gives faster solves!



Disjunctive Branch-and-Cut

[Stubbs and Mehrotra, 1999] for convex, binary MINLP:

$$\underset{\eta, x}{\text{minimize}} \quad \eta \quad \text{s.t.} \quad \eta \geq f(x), \quad c(x) \leq 0, \quad x \in X, \quad x_i \in \{0, 1\} \quad \forall i \in I$$

Node in BnB tree with solution x' , and $0 < x'_j < 1$ for $j \in I$

Relaxation: $\mathcal{C} = \{x \in X \mid f(x) \leq \eta, \quad c(x) \leq 0, \quad 0 \leq x_i \leq 1\}$

Let $I_0, I_1 \subseteq I$ index sets of 0-1 vars fixed to zero or one

Goal: Generate a valid inequality that cuts off x'

Consider two disjoint sets (“feasible sets after branching on x_j ”)

$$\mathcal{C}_j^0 = \{x \in \mathcal{C} \mid x_j = 0, \quad 0 \leq x_i \leq 1 \quad \forall i \in I, i \neq j\},$$

$$\mathcal{C}_j^1 = \{x \in \mathcal{C} \mid x_j = 1, \quad 0 \leq x_i \leq 1 \quad \forall i \in I, i \neq j\}.$$

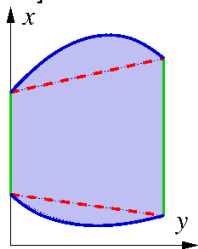
... and find description of convex hull: $\tilde{M}_j(\mathcal{C}) = \text{conv}(\mathcal{C}_j^0 \cup \mathcal{C}_j^1)$



Disjunctive Cuts for MINLP

Extension of disjunctive cuts from MILP, [Balas, 1979]
Continuous relaxation

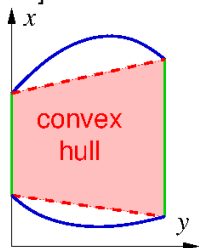
- $\mathcal{C} := \{x \mid c(x) \leq 0, 0 \leq x_I \leq 1, 0 \leq x_C \leq U\}$



Disjunctive Cuts for MINLP

Extension of disjunctive cuts from MILP, [Balas, 1979]
Continuous relaxation

- $\mathcal{C} := \{x | c(x) \leq 0, 0 \leq x_I \leq 1, 0 \leq x_C \leq U\}$
- $\mathcal{C} := \text{conv}(\{x \in \mathcal{C} \mid x_I \in \{0, 1\}^p\})$



Disjunctive Cuts for MINLP

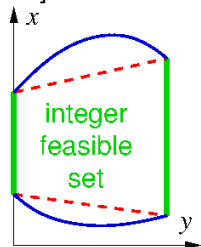
Extension of disjunctive cuts from MILP, [Balas, 1979]
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- $\mathcal{C} := \{x | c(x) \leq 0, 0 \leq x_I \leq 1, 0 \leq x_C \leq U\}$
- $\mathcal{C} := \text{conv}(\{x \in \mathcal{C} \mid x_I \in \{0, 1\}^p\})$
- $\mathcal{C}_j^{0/1} := \{x \in \mathcal{C} \mid x_j = 0/1\}$

$$\text{let } \mathcal{M}_j(\mathcal{C}) := \left\{ \begin{array}{l} z = \lambda_0 u_0 + \lambda_1 u_1 \\ \lambda_0 + \lambda_1 = 1, \lambda_0, \lambda_1 \geq 0 \\ u_0 \in \mathcal{C}_j^0, u_1 \in \mathcal{C}_j^1 \end{array} \right\}$$

$\Rightarrow \mathcal{P}_j(\mathcal{C}) := \text{projection of } \mathcal{M}_j(\mathcal{C}) \text{ onto } z$

$\Rightarrow \mathcal{P}_j(\mathcal{C}) = \text{conv}(\mathcal{C} \cap x_j \in \{0, 1\})$ and $\mathcal{P}_{1\dots p}(\mathcal{C}) = \mathcal{C}$



Disjunctive Cuts

Snag: Description of convex hull is **nonconvex**:

$$\text{let } \mathcal{M}_j(\mathcal{C}) := \left\{ \begin{array}{l} z = \lambda_0 u_0 + \lambda_1 u_1 \\ \lambda_0 + \lambda_1 = 1, \lambda_0, \lambda_1 \geq 0 \\ u_0 \in \mathcal{C}_j^0, u_1 \in \mathcal{C}_j^1 \end{array} \right\}$$

⇒ **need global optimization solvers for separation problem**

⇒ prohibitive; instead use convex formulation: $\tilde{\mathcal{M}}_j(\mathcal{C})$



Disjunctive Cuts

Can describe $\tilde{M}_j(\mathcal{C})$ with perspective \mathcal{P}_{c_i}

$$\tilde{M}_j(\mathcal{C}) = \left\{ (x_F, v_0, v_1, \lambda_0, \lambda_1) \left| \begin{array}{l} v_0 + v_1 = x_F, \quad v_{0j} = 0, \quad v_{1j} = \lambda_1 \\ \lambda_0 + \lambda_1 = 1, \quad \lambda_0, \lambda_1 \geq 0 \\ \lambda_0 c_i (v_0 / \lambda_0) \leq 0, \quad 1 \leq i \leq m \\ \lambda_1 c_i (v_1 / \lambda_1) \leq 0, \quad 1 \leq i \leq m \end{array} \right. \right\},$$

Obtain a convex separation NLP ...



Disjunctive Cuts: Separation NLP

Goal: Find \hat{x} closest to fractional solution x' in convex hull

$$\text{BC-SEP}(x', j) \begin{cases} \text{minimize } \|x - x'\|, \\ \text{subject to } (x, v_0, v_1, \lambda_0, \lambda_1) \in \tilde{M}_j(\mathcal{C}) \\ x_i = 0, \forall i \in I_0 \\ x_i = 1, \forall i \in I_1. \end{cases}$$

optimal solution \hat{x} with multipliers π_F for equality $v_0 + v_1 = x_F$

Theorem

Optimal dual solution of $(\text{BC-SEP}(x', j))$, then following cut is valid and eliminates x' :

$$\pi_F^T x_F \leq \pi_F^T \hat{x}_F$$



Disjunctive Cuts: Example

Consider following MINLP example

$$\begin{cases} \text{minimize}_{x_1, x_2} & x_1 \\ \text{subject to} & (x_1 - \frac{1}{2})^2 + (x_2 - \frac{3}{4})^2 \leq 1 \\ & -2 \leq x_1 \leq 2 \\ & x_2 \in \{0, 1\} \end{cases}$$

\Rightarrow solution of NLP relaxation: $x' = (x'_1, x'_2) = (-\frac{1}{2}, \frac{3}{4})$

Solve $(x_1 - \frac{1}{2})^2 + (x_2 - \frac{3}{4})^2 \leq 1$ for x_1 , given $x_2 = 0$ and $x_2 = 1$:

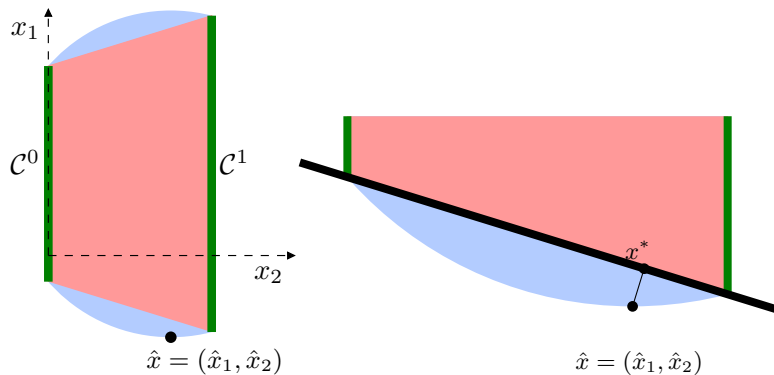
$$C^0 = \left\{ (x_1, 0) \in \mathbb{R} \times \{0, 1\} \mid 2 - \sqrt{7} \leq 4x_1 \leq 2 + \sqrt{7} \right\},$$

$$C^1 = \left\{ (x_1, 1) \in \mathbb{R} \times \{0, 1\} \mid 2 - \sqrt{15} \leq 4x_1 \leq 2 + \sqrt{15} \right\}.$$

Solving (BC-SEP($x', 2$)), we find the cut $x_1 + 0.3x_2 \geq -0.166$



Disjunctive Cuts: Example



Convex hull, relaxation, and disjunctive cut

Lifting Disjunctive Cuts

Cuts are only valid for sub-tree rooted at relaxation

To obtain globally valid cut

$$\pi^T x \leq \pi^T \hat{x}$$

assign

$$\pi_i = \min\{e_i^T H_0^T \mu_0, e_i^T H_1^T \mu_1\}, \quad i \notin F$$

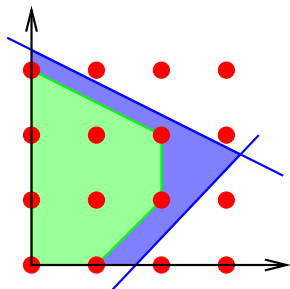
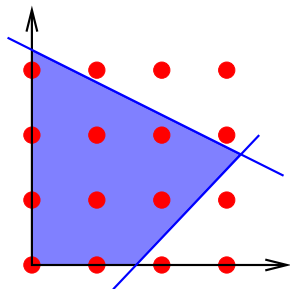
where e_i is i^{th} unit vector, F set of “free” variables and

- $\mu_0 = (\mu_{0F}, 0)$ and μ_{0F} multiplier of perspective $\mathcal{P}_c(v_0, \lambda_0) \leq 0$
- $\mu_1 = (\mu_{1F}, 0)$ and μ_{1F} multiplier of perspective $\mathcal{P}_c(v_1, \lambda_1) \leq 0$
- H_0, H_1 matrices of subgradient rows $\partial_v \mathcal{P}_{c_i}(v_j, \lambda_j)^T$, for $j = 0, 1$

Preferred norm for cut generation, $(\text{BC-SEP}(x', j))$, is ℓ_∞ -norm

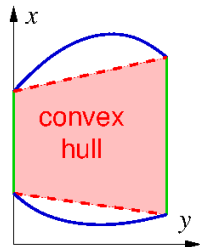
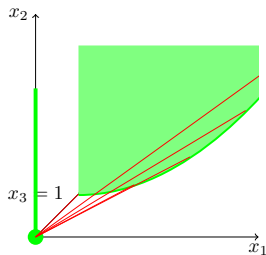


Summary and Teaching Points



Classes of Cuts

- 1 Perspective cuts
- 2 Disjunctive cuts





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